Machine Learning

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7.1. Characteristics of Support Vector Machine

• **Feed-forward Neural Network (Perceptron, MLP, RBFN..)**

- Stochastic algorithm
- Generalizes well but need a lot of tuning
- Can be learned in incremental fashion
- To learn complex functions: use hidden layers

• **SVM**

- Deterministic algorithm
- Nice Generalization with few parameters to tune
- Hard to learn quadratic programming techniques
- Using kernel tricks to learn very complex functions

7.2. Linear Separator and Perceptron

• **Linear Separator**

$$
g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0 \qquad \quad L = \left\{ \mathbf{w}^T \mathbf{x} + w_0 = 0 \right\}
$$

• For any two points $x_1, x_2 \in L$

• Define unit normal vector
$$
\mathbf{w}^* = \mathbf{w}/||\mathbf{w}||
$$

- For any point $x_0 \in L$,
- Distance of any x to L,

• The geometric margin of example $\langle x_i, y_i \rangle$ with respect to the hyperplane

 $\boldsymbol{w}^T(\boldsymbol{x}_1-\boldsymbol{x}_2)=0$

$$
y_i \cdot \frac{\boldsymbol{w}^T \boldsymbol{x} + w_0}{\|\boldsymbol{w}\|}, \quad y_i \in \{-1, +1\}
$$

• A point is misclassified iff its margin is negative

Perceptron Learning Algorithm

• To minimize

$$
D(\boldsymbol{w},w_0) = -\sum_{i \in M} y_i (\boldsymbol{w}^T \boldsymbol{x}_i + w_0)
$$

 $\frac{\partial D(\boldsymbol{w},\boldsymbol{w}_0)}{\partial \boldsymbol{w}} = -\sum_{i \in M} y_i \boldsymbol{x}_i \hspace{1cm} \frac{\partial D(\boldsymbol{w},\boldsymbol{w}_0)}{\partial \boldsymbol{w}_0} = -\sum_{i \in M} y_i$

• Gradient

Perceptron Algorithm: Dual Representation

• α_i : a count of the number of times that example *i* was misclassified

 \sim

- Initial weights are all zeros
- Then, final weights are

the control of the control of the con-

$$
\textit{\textbf{w}}{=}\sum_{i=1}^{n}\alpha_{i}y_{i}\textit{\textbf{x}}_{i}\qquad \ \ w_{0}={}\sum_{i=1}^{n}\alpha_{i}y_{i}
$$

• The output of linear predictor is

$$
h(\mathbf{x}) = sign(\mathbf{w}^T \mathbf{x} + w_0) = sign \sum_{i=1}^n \alpha_i y_i (\mathbf{x}_i^T \mathbf{x} + 1)
$$

7.3. Support Vector Machine

- Maximizing the margin
- The decision boundary: determined by a subset of the data points, known as support vectors (indicated by the circles).

Support Vector Machine

- **Support vector machines**
	- Names a whole family of algorithms of the **maximum margin separator**. The idea is to find the separator with the maximum margin from all the data points.
- Optimization problem

• Set $\|w\|$ to $1/C$

 $\min_{w_0,\mathbf{w}} \frac{1}{2} (\|\mathbf{w}\|^2)$ subject to $y_i(\mathbf{w}^T \mathbf{x}_i + w_0) \ge 1$ $i = 1,2,..,n$

Support Vector Machine: Formulation

• **Quadratic optimization problem**

 $\min_{w_0, \mathbf{w}_0^T} \frac{1}{2} (\|\mathbf{w}\|)^2$ subject to $y_i(\mathbf{w}^T \mathbf{x}_i + w_0) \ge 1$ $i = 1, 2, ..., n$

• Lagrangian formulation of constrained optimization

$$
\min_{w_0, \mathbf{w}} \max_{\alpha \geq 0} L(w_0, \mathbf{w}, \alpha) = \frac{1}{2} (\|\mathbf{w}\|)^2 - \sum_{i=1}^n \alpha_i \big[y_i (\mathbf{w}^T \mathbf{x}_i + w_0) - 1 \big]
$$

• Kuhn-Tucker Theorem $\min_{w_0,\boldsymbol{w}}\max_{\alpha\geq 0}L(w_0,\boldsymbol{w},\alpha)=\max_{\alpha\geq 0}\min_{w_0,\boldsymbol{w}}L(w_0,\boldsymbol{w},\alpha)$

$$
\frac{\partial L(w_0, w, \alpha)}{\partial w} = w - \sum_{i=1}^n \alpha_i y_i x_i = 0 \qquad w = \sum_{i=1}^n \alpha_i y_i x_i
$$

$$
\frac{\partial L(w_0, w, \alpha)}{\partial w_0} = - \sum_{i=1}^n \alpha_i y_i = 0 \qquad \sum_{i=1}^n \alpha_i y_i = 0
$$

Support Vector Machine: Formulation & Solution

$$
\mathbf{w} = \sum_{i=1}^{n} \alpha_i y_i \mathbf{x}_i
$$
\n
$$
\min_{w_0, \mathbf{w}} \max_{\alpha \geq 0} L(w_0, \mathbf{w}, \alpha) = \frac{1}{2} (\|\mathbf{w}\|)^2 - \sum_{i=1}^{n} \alpha_i [y_i(\mathbf{w}^T \mathbf{x}_i + w_0) - 1]
$$
\n
$$
\sum_{i=1}^{n} \alpha_i y_i = 0
$$
\n
$$
L(\alpha) = \sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n} \alpha_j \alpha_k y_j y_k(\mathbf{x}_j^T \mathbf{x}_k)
$$

Maximize $L(\alpha)$ subject to $\alpha \ge 0$ and $\sum_i \alpha_i y_i = 0$

Finding optimal α_i : computationally tractable quadratic programming problem Support Vector: points with margin=1

$$
y_i(\boldsymbol{w}^T\!\boldsymbol{x}_i + w_0) = 1 \qquad \qquad w_0 = y_i - \boldsymbol{w}^T\!\boldsymbol{x}_i
$$

Support Vector Machines

- What if the problem is not linearly separable?
- Introduce slack variables
	- Need to minimize:

$$
L(w, \xi) = \frac{\|\vec{w}\|^2}{2} + C \left(\sum_{i=1}^{m} \xi_i\right)
$$

Subject to:

$$
y_i(\vec{w} \cdot \vec{x}_i + b) \ge 1 \le \xi_i
$$
 for all (\vec{x}_i, y_i) in D

Support Vector Machines

• What if decision boundary is not linear?

A nonseparable dataset in a two-dimensional space R^2 , and the same dataset mapped onto threedimensions with the third dimension being x²+y² (source: http://www.eric-kim.net/eric-kim-net/posts/1/kernel_trick.html)

The decision boundary is shown in green, first in the three-dimensional space (left), then back in the twodimensional space (right). Same source as previous image.

예제 7.3-1

그림과 같이 2차원 공간상에 두 개의 클래스에 해당하는 점집합이 주어졌다. 사각형 클래스 는 $y_i = 1$, 원형 클래스는 $y_i = -1$ 이라고 두고서 퍼셉트론의 이중적 표현에 의한 학습을 두 epoch 동안 반복하여 보아라. 그리고, Support Vector의 지점을 구하고, 이를 근거로 SVM 에 의한 구분자를 구하여라.

풀이

먼저, 6개의 점들의 순서를 각 클래스가 섞이도록 $\mathbf{x}_1(2,4)$, $\mathbf{x}_2(1,1)$, $\mathbf{x}_3(3,4)$, $\mathbf{x}_4(1,2)$, $x_5(4,2)$, $x_6(2,1)$ 와 같이 정하였다. 이 점들 사이의 내적을 표로 만들면 위와 같다. 이 표를 활용하여 수식 $\alpha_i (i = 1, 2, ..., 6)$ 를 변경시킨다. 여기서, $\pmb{x}_1, \pmb{x}_3, \pmb{x}_5 = y_i = 1$ 이고 나머지 점 들은 $y_i = -1$ 이다.

우선, 첫 단계로 모든 $\alpha_i (i = 1, 2, ..., 6)$ 를 영으로 설정한다.

첫 epoch에서 $\boldsymbol{x}_i (i = 1, 2, ..., 6)$ 을 순차적으로 입력하면

$$
\mathbf{x}_i(i=1) \, \mathrm{Q}[\vec{\mathbf{e}}] : \; \mathbf{E} \equiv \alpha_i \leftarrow \; \mathbf{Q} \cdot \mathbf{0} \, \mathbf{E} \; \mathbf{y}_1 \sum_{j=1}^n \alpha_j y_j(\mathbf{x}_j^T \mathbf{x}_1 + 1) = 0, \; \alpha_1 := \alpha_1 + 1 = 1
$$

$$
\pmb{x}_i(i=2)\,\mathbf{Q}\,\mathbf{E}: \; y_2\sum_{j=1}^n\alpha_jy_j(\pmb{x}_j^T\pmb{x}_2+1)=-1\,[1\times(6+1)]=-7, \; \alpha_2:=\alpha_2+1=1
$$

$$
\mathbf{x}_3 \, \mathrm{Q} \, \mathrm{H} : y_3 \sum_{j=1}^n \alpha_j y_j (\mathbf{x}_j^T \mathbf{x}_3 + 1) = 1 [1 \times (22 + 1) - 1 \times (7 + 1)] = 15, \ \alpha_3 := \alpha_3 = 0
$$

$$
\boldsymbol{x}_4 \, \mathbf{Q} \, \mathbf{E} : \ y_4 \sum_{j=1}^n \alpha_j y_j (\boldsymbol{x}_j^T \boldsymbol{x}_4 + 1) = -7, \ \alpha_4 := \alpha_4 + 1 = 1
$$

두 번째 epoch에서 다시 $\mathbf{x}_i (i = 1, 2, ..., 6)$ 을 순차적으로 입력하면

$$
\mathbf{x}_1 \, \mathbf{Q} \, \mathbf{E} : \ y_1 \sum_{j=1}^n \alpha_j y_j (\mathbf{x}_j^T \mathbf{x}_1 + 1) = -\, 6, \ \alpha_1 := \alpha_1 + 1 = 2
$$

$$
\pmb{x}_2 \, \mathrm{QI} \, \mathrm{\overrightarrow{e}} \, : \, y_2 \sum_{j \, = \, 1}^n \alpha_j y_j \big(\pmb{x}_j^T \pmb{x}_2 + 1 \big) \, \mathrm{=}\, -\, 3 \, , \, \, \alpha_2 := \alpha_2 + 1 \, \mathrm{=}\, 2
$$

$$
\boldsymbol{x}_3 \text{Q} \text{H} : y_3 \sum_{j=1}^n \alpha_j y_j (\boldsymbol{x}_j^T \boldsymbol{x}_3 + 1) = 7, \ \alpha_3 := \alpha_3 = 0
$$

$$
\mathbf{x}_5 \, \mathbf{Q} \, \mathbf{E} : \ y_5 \sum_{j=1}^n \alpha_j y_j (\mathbf{x}_j^T \mathbf{x}_5 + 1) = -11, \ \alpha_5 := \alpha_5 + 1 = 1
$$

그림에서 Support Vector는 사각 클래스의 $x_1(2,4), x_5(4,2)$ 와 원 클래스의 $x_4(1,2),$ $x_6(2,1)$ 이다. 이 4개의 점들을 기준으로 x_1, x_5 에서는 +1의 값을 가지고 x_4, x_6 에서는 -1 의 값을 가지는 선형 구분자는 $g(\mathbf{x}) = \frac{2}{3}(x_1 + x_2) - 3$ 이다. 이를 그림으로 그리면 아래와 같다.

7.4. Application of SVM[10] [Suh-Yeon Dong, et al. 2016]

Objective: Discriminate agreement and disagreement to the given selfrelevant sentence in the single-trial level.

- **Stimuli:** 74 Korean sentences from the Minnesota Multiphasic Personality inventory-II (MMPI-II). Sentence contents are related to personal experience.
- **Presentation:** Considering the Subject-object-verb (SOV) typology of the Korean language, each sentence was separated into two parts: the verb (sentence ending) and the remainder of the sentence (contents).

Experiment Procedure

Experiment Procedure

fMRI Experiment (19 subjects)

Image acquisition

3T MR scanner (Siemens Magnetom Vero, Germany)

- MR-compatible goggle (NordicNeuroLab Visual systmes, Norway)
- Gradient-echo echo-planar imaging (EPI) sequence (36 slices; thickness = 4 mm; no gap between slices; $FOV =$ 220 \times 220 mm; matrix = 64 \times 64; TE = 28 ms; TR = 2.0 s; flip angle = 90 °; voxel size 3.4 mm \times 3.4 mm \times 4 mm)

Preprocessing

- (SPM8) Realign, coregister, segmentation, normalize, and smooth
- **EEG Experiment (9 subjects) •** Data acquisition

- BrainAmp system (Brain Products GmbH, Germany)
- 32-channel EEG cap (BrainCap)
- Eyetracker x120 (Tobii Technology, Sweden)

Preprocessing

- 60Hz notch filtering and 1Hz high-pass filtering
- Offline re-referencing to average (except EOG and ECG)
- Artifact Removal: EOG and ECG-related independent components
- Trial rejection: Reject trials whose absolute amplitude is over 70 μV

Feature Selection

Referring to the fMRI results, responses at frontal channels are considered.

▪ **Time-frequency Representations (TFRs)**

Average TFR difference: Agree - Disagree

Gamma 35-45Hz 350-550ms (a) Gamma 35-45Hz 350-550ms

Beta1 14-17Hz 800-1000ms Beta2 20-26Hz 300-450ms (b) Beta2 20-26Hz 300-450ms(c) Beta1 14-17Hz 800-1,000ms

Alpha 9-12Hz 300-700ms Theta 5-7Hz 400-1000ms (d) Alpha 9-12Hz 300-700ms(e) Theta 5-7Hz 400-1,000ms

-180 0 180

Channel Selection

• Channel selection using the Fisher score

^[19]
The Fisher score for the ith channel:

 n_k : sample size of $k^{\rm th}$ class μ^i_k : mean of k^th class in the i^th channel σ_k^i : std of k^{th} class in the i^{th} channel μ^i : mean of entire data in the i^{th} channel c : Total number of classes (here, $c = 2$)

Classification

- **EXECT** Subject-dependent classification with increasing the number of selected channels
- Average accuracy using 5-fold cross validation
- SVM classifier with linear and RBF kernels (LIBSVM)

