

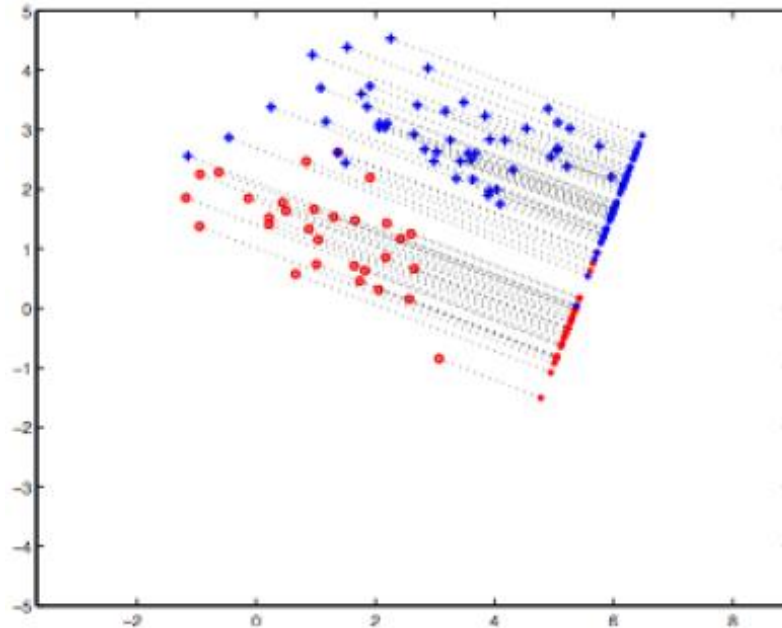
Machine Learning

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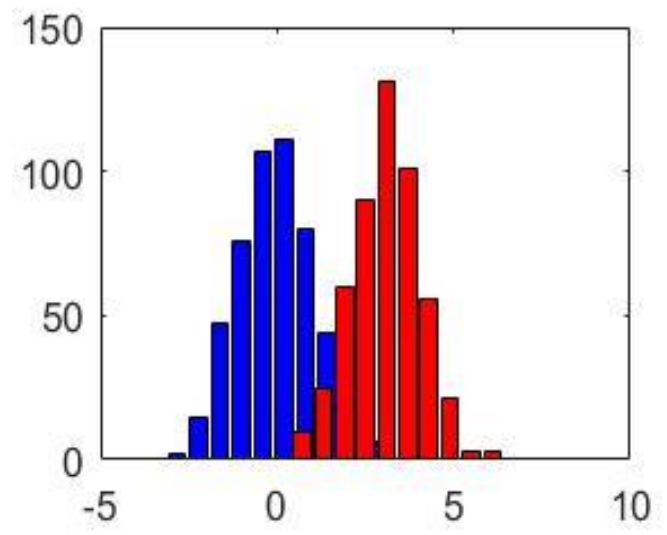
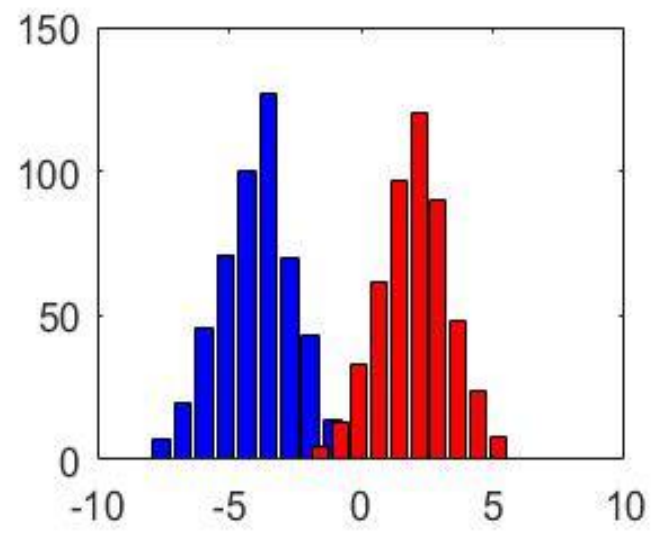
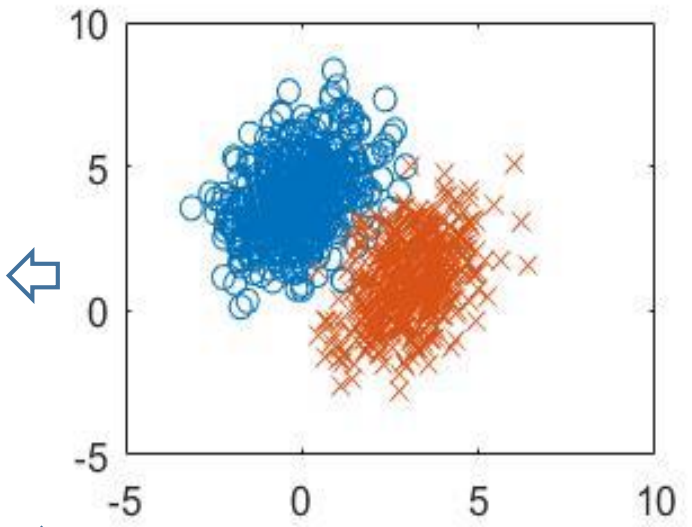
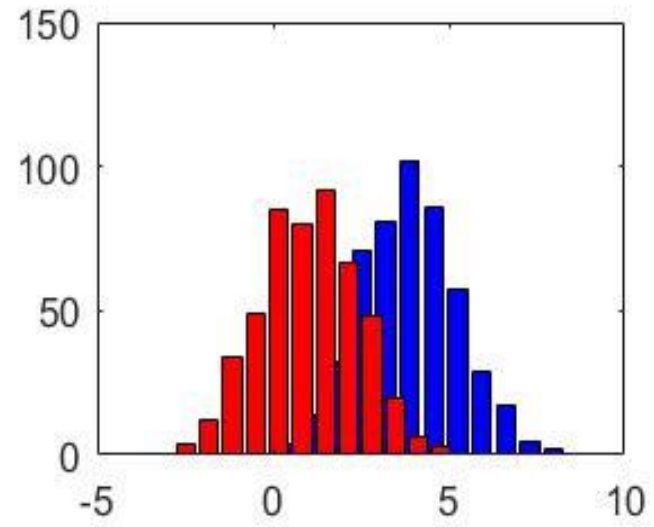
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3.1. Linear Discriminant Analysis (LDA)

- Problem: Given a set of data points, each of which is labelled with a class, find the best set of basis vectors for projecting the data points such that classification is improved.
- Idea: Form the projection such that the variability across the different classes is maximized, while the variability within each class is minimized.

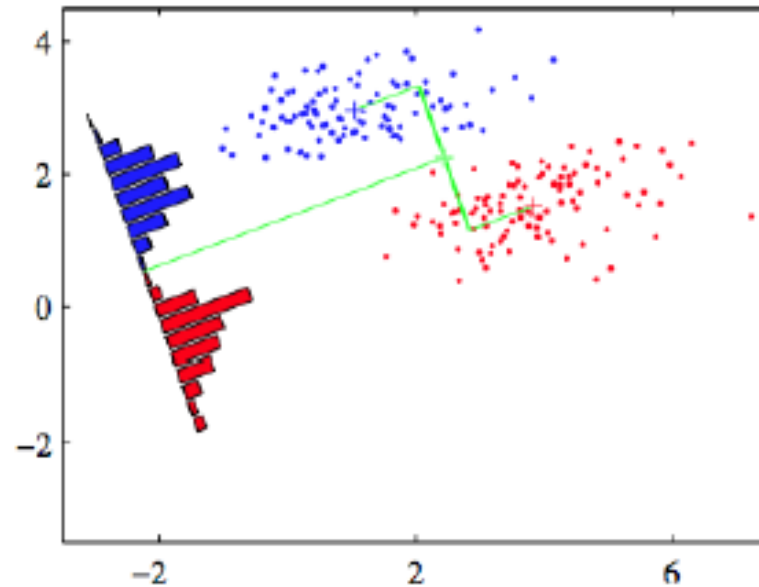
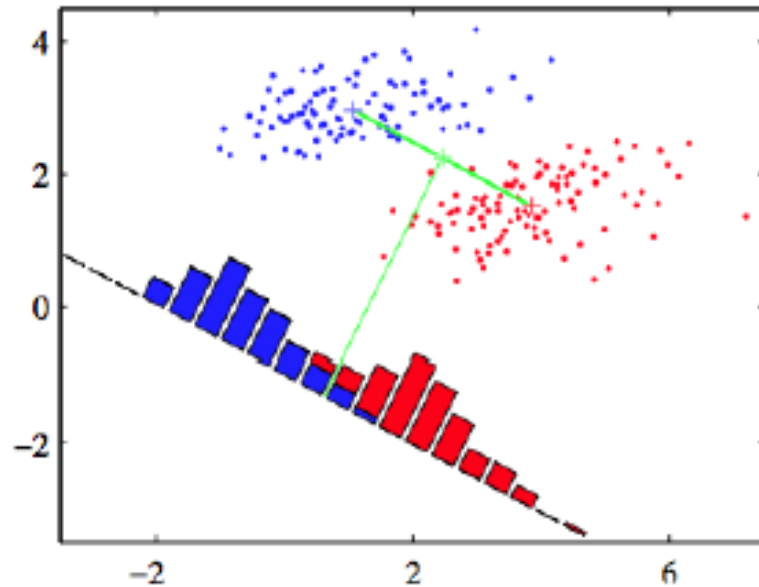


Which one is the best projection?



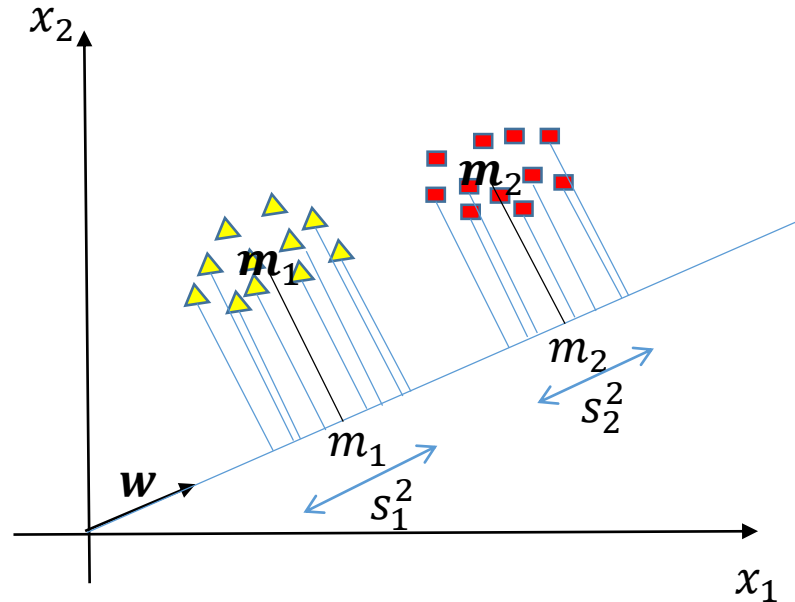
LDA: Maximize Difference of Means

- Considering the simple problem of projecting onto one dimension
- The two classes should be well separated in this single dimension
- A simple idea is to maximize the difference of the means in the projected space
- What is a problem with this solution?



LDA: A Better Idea

- Fisher's idea: Fisher's linear discriminant
 - Maximize a function that will give a large separation between the projected class means
 - While also giving a small variance within each class, thereby minimizing the class overlap



3.2. Projection with Basis Vectors

- Point $A = (a_1, a_2)^T$
- Basis Vector $\mathbf{w} = (w_1, w_2)^T$
- Projection $\mathbf{w}^T A = w_1 a_1 + w_2 a_2$

참조:

T(transpose)는 행렬 혹은 벡터에서 행과 열의 위치를 교환하는 이항 연산자이다. 즉,

$$(a_1, a_2)^T = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \quad (3.2.4)$$

이고

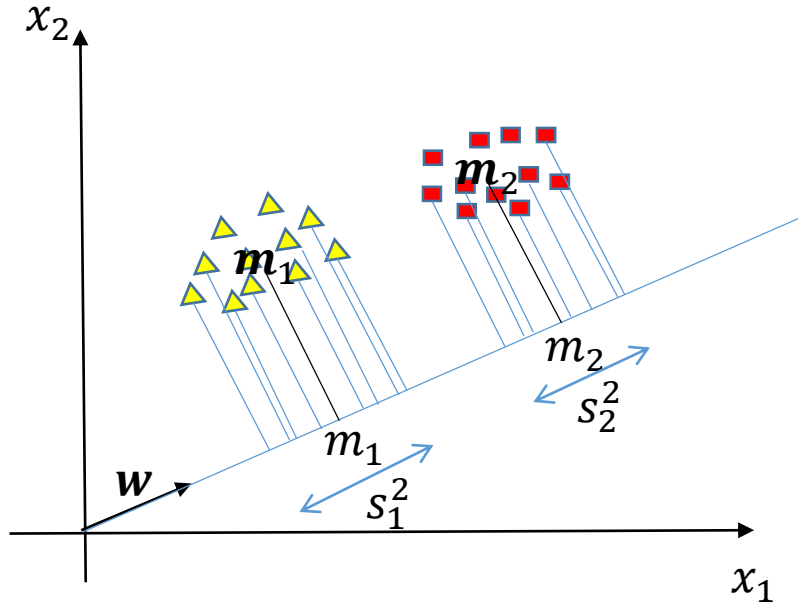
$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}^T = \begin{pmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{pmatrix} \quad (3.2.5)$$

이다. 또한 행렬 A와 B의 곱에 대하여 이항 연산자 T를 적용하면

$$(AB)^T = B^T A^T \quad (3.2.6)$$

이 된다.

3.3. LDA Formulation



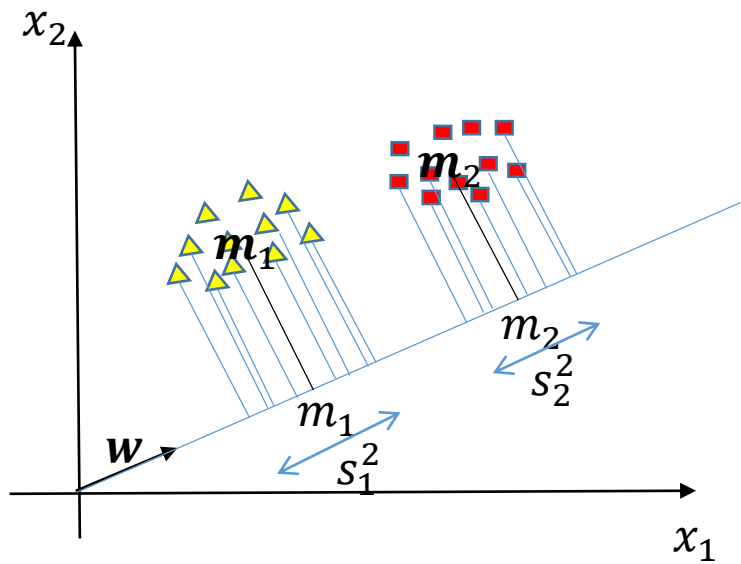
$$J(\mathbf{w}) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2} \quad (3.3.1)$$

$$m_1 = \frac{\sum_{i \in C_1} \mathbf{w}^T \mathbf{x}^i}{N_1} = \frac{\sum_t \mathbf{w}^T \mathbf{x}^t r^t}{\sum_t r^t} = \mathbf{w}^T \frac{\sum_t \mathbf{x}^t r^t}{\sum_t r^t} = \mathbf{w}^T m_1 \quad (3.3.2)$$

$$s_1^2 = \sum_t (\mathbf{w}^T \mathbf{x}^t - m_1)^2 r^t \quad (3.3.3)$$

$$\begin{aligned} (m_1 - m_2)^2 &= (\mathbf{w}^T m_1 - \mathbf{w}^T m_2)^2 = (\mathbf{w}^T (m_1 - m_2))^2 \\ &= \mathbf{w}^T (m_1 - m_2)(m_1 - m_2)^T \mathbf{w} = \mathbf{w}^T S_B \mathbf{w} \end{aligned} \quad (3.3.4)$$

$$S_B = (m_1 - m_2)(m_1 - m_2)^T \quad (3.3.5)$$



$$J(\mathbf{w}) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2} \quad (3.3.1)$$

$$\begin{aligned} s_1^2 &= \sum_t (\mathbf{w}^T \mathbf{x}^t - m_1)^2 r^t = \sum_t (\mathbf{w}^T \mathbf{x}^t - \mathbf{w}^T \mathbf{m}_1)^2 r^t = \sum_t (\mathbf{w}^T (\mathbf{x}^t - \mathbf{m}_1))^2 r^t \\ &= \sum_t \mathbf{w}^T (\mathbf{x}^t - \mathbf{m}_1) (\mathbf{x}^t - \mathbf{m}_1)^T \mathbf{w} r^t = \mathbf{w}^T S_1 \mathbf{w} \end{aligned} \quad (3.3.6)$$

$$S_1 = \sum_t (\mathbf{x}^t - \mathbf{m}_1) (\mathbf{x}^t - \mathbf{m}_1)^T r^t \quad (3.3.7)$$

$$s_1^2 + s_2^2 = \mathbf{w}^T S_W \mathbf{w} \quad (3.3.8)$$

$$S_W = S_1 + S_2 \quad (3.3.9)$$

$$J(\mathbf{w}) = \frac{\mathbf{w}^T S_B \mathbf{w}}{\mathbf{w}^T S_W \mathbf{w}} \quad (3.3.10)$$

예제 3.3-1

행렬 $A = (a_{ij})$ 가 $d \times d$ 정방행렬이고, 다음 함수

$$g(\mathbf{w}) = \mathbf{w}^T \mathbf{A} \mathbf{w} = \sum_{i=1}^d \sum_{j=1}^d w_i w_j a_{ij}$$

에 대하여 $\frac{\partial g}{\partial \mathbf{w}}$ 를 구하여라.

풀이

문제로 주어진 함수를 더 자세히 적으면

$$g(\mathbf{w}) = \mathbf{w}^T \mathbf{A} \mathbf{w} = \sum_{i=1}^d \sum_{j=1}^d w_i w_j a_{ij} = w_k \sum_{j=1}^d w_j a_{kj} + \sum_{i \neq k} w_i \sum_{j=1}^d w_j a_{ij}$$

이 된다. 여기에, $\sum_{j=1}^d w_j a_{kj} = w_k a_{kk} + \sum_{j \neq k} w_j a_{kj}$ 와 $\sum_{j=1}^d w_j a_{ij} = w_k a_{ik} + \sum_{j \neq k} w_j a_{ij}$ 를 대입하면

$$g(\mathbf{w}) = w_k \sum_{j \neq k} w_j a_{kj} + w_k^2 a_{kk} + \sum_{i \neq k} w_i w_k a_{ik} + \sum_{i \neq k} \sum_{j \neq k} w_i w_j a_{ij}$$

이다. 따라서,

$$\frac{\partial g(\mathbf{w})}{\partial \mathbf{w}} = \sum_{j \neq k} w_j a_{kj} + 2w_k a_{kk} + \sum_{i \neq k} w_i a_{ik} = \sum_{j=1}^d w_j a_{kj} + \sum_{i=1}^d w_i a_{ik} = \mathbf{A} \mathbf{w} + \mathbf{A}^T \mathbf{w}$$

이 된다.

Maximizing

$$J(\mathbf{w}) = \frac{\mathbf{w}^T S_B \mathbf{w}}{\mathbf{w}^T S_W \mathbf{w}} \quad (3.3.10)$$

From $\frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} = 0$,

$$2S_B \mathbf{w} (\mathbf{w}^T S_W \mathbf{w}) - (\mathbf{w}^T S_B \mathbf{w}) 2S_W \mathbf{w} = 0 \quad (3.3.11)$$

$$S_B \mathbf{w} (\mathbf{w}^T S_W \mathbf{w}) = (\mathbf{w}^T S_B \mathbf{w}) S_W \mathbf{w} \quad (3.3.12)$$

$$S_B \mathbf{w} = \frac{(\mathbf{w}^T S_W \mathbf{w})}{(\mathbf{w}^T S_B \mathbf{w})} S_W \mathbf{w} = \lambda S_W \mathbf{w} \quad (3.3.13)$$

$$S_B = (\mathbf{m}_1 - \mathbf{m}_2)(\mathbf{m}_1 - \mathbf{m}_2)^T \quad (3.3.5) \implies S_B \mathbf{w} = (\mathbf{m}_1 - \mathbf{m}_2) \underbrace{(\mathbf{m}_1 - \mathbf{m}_2)^T \mathbf{w}}_{\text{scalar}} \quad (3.3.14)$$

$$\mathbf{w} = S_W^{-1} (\mathbf{m}_1 - \mathbf{m}_2) \quad (3.3.15)$$

참조: 벡터의 미분

d 차원 벡터 $\mathbf{w} = (w_1, w_2, \dots, w_d)^T$ 에 대한 미분 가능한 스칼라 함수 g 가

$$g(w_1, w_2, \dots, w_d) = g(\mathbf{w}) \quad (3.3.16)$$

로 주어졌다. 그러면, 함수 g 의 벡터 \mathbf{w} 에 대한 미분은

$$\frac{\partial g}{\partial \mathbf{w}} = \begin{pmatrix} \frac{\partial g}{\partial w_1} \\ \vdots \\ \frac{\partial g}{\partial w_d} \end{pmatrix} \quad (3.3.17)$$

이다. 또한 2차 미분은

$$\frac{\partial^2 g}{\partial \mathbf{w}^2} = \begin{pmatrix} \frac{\partial^2 g}{\partial w_1^2} & \dots & \frac{\partial g}{\partial w_1 \partial w_d} \\ \vdots & & \vdots \\ \frac{\partial g}{\partial w_d \partial w_1} & \dots & \frac{\partial^2 g}{\partial w_d^2} \end{pmatrix} \quad (3.3.18)$$

이 된다. 벡터 값을 지닌 함수 g 가

이 된다. 벡터 값을 지닌 함수 g 가

$$g(\mathbf{w}) = \begin{pmatrix} g_1(\mathbf{w}) \\ \vdots \\ g_n(\mathbf{w}) \end{pmatrix} \quad (3.3.19)$$

로 주어지면 g 의 \mathbf{w} 에 대한 Jacobian 행렬은

$$\frac{\partial g}{\partial \mathbf{w}} = \begin{pmatrix} \frac{\partial g_1}{\partial w_1} & \cdots & \frac{\partial g_n}{\partial w_1} \\ \vdots & & \vdots \\ \frac{\partial g_1}{\partial w_d} & \cdots & \frac{\partial g_n}{\partial w_d} \end{pmatrix} \quad (3.3.20)$$

이다. 또한

$$\frac{\partial f(\mathbf{w})g(\mathbf{w})}{\partial \mathbf{w}} = \frac{\partial f(\mathbf{w})}{\partial \mathbf{w}} g(\mathbf{w}) + f(\mathbf{w}) \frac{\partial g(\mathbf{w})}{\partial \mathbf{w}} \quad (3.3.21)$$

$$\frac{\partial f(\mathbf{w})/g(\mathbf{w})}{\partial \mathbf{w}} = \left[\frac{\partial f(\mathbf{w})}{\partial \mathbf{w}} g(\mathbf{w}) - f(\mathbf{w}) \frac{\partial g(\mathbf{w})}{\partial \mathbf{w}} \right] / g^2(\mathbf{w}) \quad (3.3.22)$$

$$\frac{\partial f(g(\mathbf{w}))}{\partial \mathbf{w}} = f'(g(\mathbf{w})) \frac{\partial g(\mathbf{w})}{\partial \mathbf{w}} \quad (3.3.23)$$

이다.

More than 2 Classes ($K > 2$)

- Projection from d -dim space to $(c-1)$ -dim space:

- $y_i = \mathbf{w}_i^T \mathbf{x}$, $i = 1, \dots, c-1$
- $\mathbf{y} = \mathbf{W}^T \mathbf{x}$ ($\mathbf{W} = d \times (c-1)$ matrix, \mathbf{w}_i is the i -th column vector)
- Within-class scatter matrix for C_i is

$$S_i = \sum_t r_i^t (\mathbf{x}^t - \mathbf{m}_i)(\mathbf{x}^t - \mathbf{m}_i)^T$$

where $r_i^t = 1$ if $x^t \in C_i$ and 0 otherwise.

- The total within-class scatter is

$$S_W = \sum_{i=1}^K S_i$$

- The between-class scatter matrix is

$$S_B = \sum_{i=1}^K N_i (\mathbf{m}_i - \mathbf{m})(\mathbf{m}_i - \mathbf{m})^T$$

where $N_i = \sum_t r_i^t$

More than 2 Classes ($K > 2$)

- The between-class scatter matrix after projection is:
- The within-class scatter matrix after projection is:
- Thus we need to find the matrix \mathbf{W} that maximizes

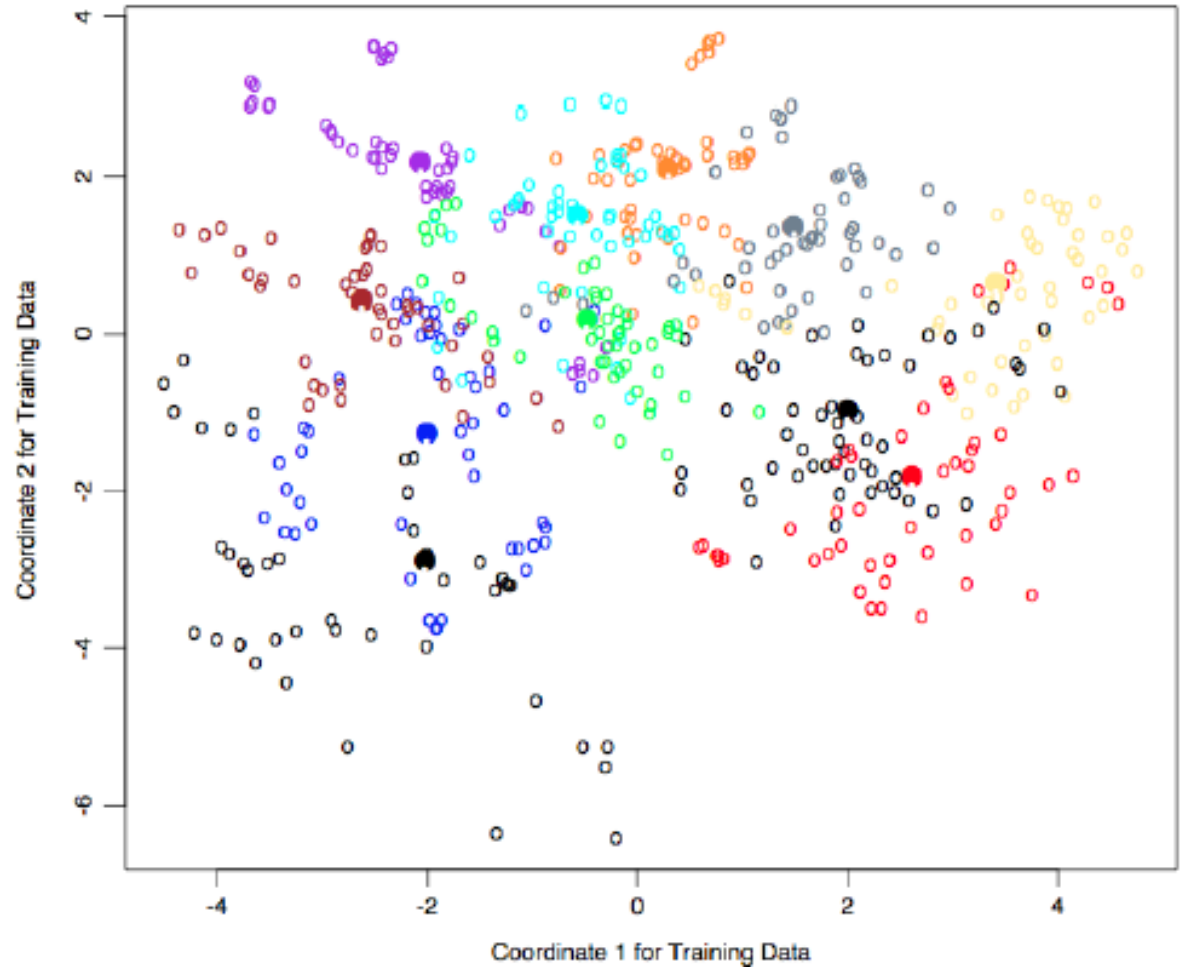
$$J(\mathbf{W}) = \frac{|\mathbf{W}^T \mathbf{S}_B \mathbf{W}|}{|\mathbf{W}^T \mathbf{S}_W \mathbf{W}|}$$

- The largest eigenvectors of $\mathbf{S}_W^{-1} \mathbf{S}_B$ are the solution.

LDA on Vowels Data

- 11 vowels from words spoken by fifteen speakers. (Source: David Deterding, Mahesan Niranjan, Tony Robinson, see Hastie book website for data)

vowel	word	vowel	word
i	heed	o	hod
I	hid	C:	hoard
E	head	U	hood
A	had	u:	who'd
a:	hard	3:	heard
Y	hud		



LDA on Vowels Data: Decision Boundaries

